

Master CMB, 1st year
Differential systems, semester 1
TP - Nonlinear ODEs

Exercise 1 (The van der Pol oscillator)

We consider the nonlinear differential equation

$$x''(t) - \mu(1 - x(t)^2)x'(t) + x(t) = 0$$

which can be rewritten under the following form

$$\begin{cases} x'(t) = \mu \left(x(t) - \frac{x(t)^3}{3} \right) + y(t) & (1a) \\ y'(t) = -x(t) & (1b) \end{cases}$$

1. Let us fix $\mu = 1$. Represent on the same graph the solutions curves (resp. the trajectories) for the following initial data: $(0, 1)$, $(3, 3)$, $(-3, -3)$. What do you observe ?
2. Determine the equilibrium point(s) of the system. According to the value of μ , illustrate the nature (local stability or instability) of the equilibrium point(s) by representing the numerical solutions associated to the linearized system(s) around the equilibrium point(s).
3. We fix again $\mu = 1$. Represent in the phase plane the nullclines associated to system (1). What is coarsely the behavior the solutions in each region of the plane ? Complete the phase portrait with the vector field and the limit cycle.
4. Compare the case $\mu = 1$ with the case $\mu = 20$. Interpret the behavior of the solutions in that latter case.

Exercise 2 (The FitzHugh Nagumo system)

We consider the following extension of the previous van der Pol system (1)

$$\begin{cases} x'(t) = \mu \left(x(t) - \frac{x(t)^3}{3} \right) + y(t) + I & (2a) \\ y'(t) = -x(t) + a - by(t) & (2b) \end{cases}$$

1. We set $\mu = 6$, $a = 1$, $b = 2$, $I = -\frac{a}{b}$.
 - (a) Determine the nullclines and the equilibrium point(s) of the system. Represent them in the phase plane with the vector field.
 - (b) Determine the nature of the equilibrium point(s) and illustrate it graphically.

2. We set $\mu = 6$, $b = I = 0$. We now study the behavior of the solutions for different values of a .
- (a) Determine the nullclines and the equilibrium point(s). What can you say about the nature of the equilibrium point(s) according to the value of the parameter a .
 - (b) Illustrate the results numerically.